

Linear Algebra: Workshop Questions 2

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1 Questions

Exercise 1.1. Let $u = \begin{pmatrix} 1 \\ 0 \\ -2 \\ 2 \end{pmatrix}$ and $v = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$.

- (a) What is the angle between u and v ?
- (b) Write down a vector $w \in \mathbb{R}^4$ which is orthogonal to both u and v .

Exercise 1.2. Let

$$A = \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{pmatrix}, \quad B = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & 0 & 1 \\ -1 & 0 & 1 \end{pmatrix}$$

- (a) Which of these two matrices is orthogonal?
- (b) The orthogonal matrix from part (a) represents a rotation. What are the axis and angle of this rotation?

Exercise 1.3. True or false? If false, give a counterexample.

- (a) Any 1-by- n matrix is in echelon form.
- (b) Let A be a matrix in reduced echelon form. If A has no free variables then the equation $Av = b$ always has a solution.

Exercise 1.4. Write this system of equations as a matrix equation. Put the corresponding augmented matrix into reduced echelon form and hence determine whether there is a solution or not.

$$\begin{aligned} 2x + 4y - 5z &= -7 \\ -x - 2y + z &= 1 \\ x + 2y &= 1 \end{aligned}$$

Exercise 1.5. (a) A system of simultaneous equations is called *overdetermined* if there are more equations than variables. It is true that overdetermined systems never have solutions?

- (b) A system of simultaneous equations is called *underdetermined* if there are more variables than equations. It is true that underdetermined systems always have solutions?